### High priority targets for transient continuous waves from glitching pulsars

Garvin Yim







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CWs Workshop, AEI, 16th June 2024 *[g.yim@pku.edu.cn](mailto:g.yim@pku.edu.cn)* Yim, Shao & Xu (submitted), [arXiv: 2406.00283](https://arxiv.org/abs/2406.00283)



## Contents

1



# Motivation: O4 run is underway

Not yet observed a continuous gravitational wave (CW) signal

### Compare different pulsar glitch models Create a list of high priority targets Objectives:

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Part I - Energy budgets from pulsar glitches Part II - Gravitational wave signal analysis Part III - Results Part IV - Summary



Part I - Energy budgets from pulsar glitches

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## Transient continuous waves



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### $\text{Duration} = \mathcal{O}(\text{Minutes})$  Duration  $\gg$  Observation time







### Duration

## Transient continuous waves





### Duration

Transient Continuous Waves



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 $h(t) = \varpi(t; t_0, T_{GW})h_{CW}(t)$ 

### $\mathcal{O}(\text{Minutes}) < \text{Duration} < \mathcal{O}(\text{Monthly})$

### $\mathbf{Duration} = \mathcal{O}(\text{Minutes})$  Duration  $\gg \text{Observation time}$















"Glitch rise" models

Model 1: Starquake (one component)

Model 2: Superfluid vortex unpinning (two components)



"Glitch rise" models





## "Postglitch" models Model 3: Transient mountain Model 4: Ekman pumping

Model 1: Starquake (one component)

Model 2: Superfluid vortex unpinning (two components)

"Glitch rise" models

Credit: Espinoza et al. (2011)





"Postglitch" models Model 3: Transient mountain Model 4: Ekman pumping

Glitch models attempt to explain the spin-up. Postglitch models are agnostic to what causes the spin-up.

Model 1: Starquake (one component)

Model 2: Superfluid vortex unpinning (two components)



Credit: Espinoza et al. (2011)





"Postglitch" models Model 3: Transient mountain Model 4: Ekman

pumping

### +2 "naïve" models, one each for oneand two- component neutron stars

"Glitch rise" models

Model 1: Starquake (one component)

Model 2: Superfluid vortex unpinning (two components)



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Glitch models attempt to explain the spin-up. Postglitch models are agnostic to what causes the spin-up.

Concerned mostly about the energy available for GW emission,  $E_{GW}$ 



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Credit: Espinoza et al. (2011)





"Postglitch" models Model 3: Transient mountain Model 4: Ekman

pumping

Model 1: Starquake (one component)

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### +2 "naïve" models, one each for oneand two- component neutron stars

"Glitch rise" models

Glitch models attempt to explain the spin-up. Postglitch models are agnostic to what causes the spin-up.

### Summary: Reduction in Δ*I* leads to an increase in ΔΩ since Δ*J* = 0

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# Model 1: Starquake (one component) model

### [Sidery et al. 2010, LSC 2011]

# One component in the sense that the angular momentum and rotational







### Summary: Reduction in Δ*I* leads to an increase in ΔΩ since Δ*J* = 0

### Model 1: Starquake (one component) model [Sidery et al. 2010, LSC 2011]

kinetic energy can be written as:  $J = IΩ$  and  $E_{rot} = IΩ<sup>2</sup>/2$ 

- One component in the sense that the angular momentum and rotational kinetic energy can be written as:  $J = I\Omega$  and  $J = I\Omega$  and  $E_{rot} = I\Omega^2/2$
- Imagine a sudden decrease in the moment of inertia  $\Delta I$ , i.e. a starquake.
- We must conserve angular momentum so Δ*J* ≈ (Δ*I*)Ω + *I*ΔΩ = 0
	- This causes the energy to change: Δ*Erot* = 1 2  $(I + \Delta I)(\Omega + \Delta \Omega)^2 - \frac{1}{2}$ 2 *I*Ω<sup>2</sup>

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Summary: Reduction in Δ*I* leads to an increase in ΔΩ since Δ*J* = 0





## Model 1: Starquake (one component) model [Sidery et al. 2010, LSC 2011]

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- We must conserve angular momentum so Δ*J* ≈ (Δ*I*)Ω + *I*ΔΩ = 0
	- This causes the energy to change: Δ*Erot* =

Assuming  $E_{GW} = \Delta E_{rot}$  this means:  $E_{GW} =$ 

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$$
E_{rot} = \frac{1}{2}(I + \Delta I)(\Omega + \Delta \Omega)^2 - \frac{1}{2}I\Omega^2
$$

$$
\vdots
$$
  $E_{GW} = \frac{1}{2}I\Omega\Delta\Omega$ 





Summary: Reduction in Δ*I* leads to an increase in ΔΩ since Δ*J* = 0

## Model 1: Starquake (one component) model [Sidery et al. 2010, LSC 2011]

# Model 2: Vortex unpinning (two component) model

### [Sidery et al. 2010, LSC 2011, Prix et al. 2011]

### Summary: Excess rotational kinetic energy of two components  $\rightarrow E_{GW}$





Two component model: superfluid (s) and crust+everything else coupled to it (c)

 $I_s \Omega_s^2$  +

Ω*s*



1

2

 $J = I_s \Omega_s + I_c \Omega_c$ 

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1

 $I_c\Omega_c^2$ 

2



 $I_c$ 



# Model 2: Vortex unpinning (two component) model

[Sidery et al. 2010, LSC 2011, Prix et al. 2011]

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- Summary: Excess rotational kinetic energy of two components  $\rightarrow E_{GW}$
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	- 2 2



External torque (e.g. magnetic dipole radiation) acts only on the crust component, so lag develops between the two components:  $ω = Ω_c - Ω_c > 0$ 

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Ω*s*

 $I_c$ 



$$
J = I_s \Omega_s + I_c \Omega_c \qquad E_{rot} =
$$

5

# Model 2: Vortex unpinning (two component) model

[Sidery et al. 2010, LSC 2011, Prix et al. 2011]

External torque (e.g. magnetic dipole radiation) acts only on the crust component, so lag develops between the two  $components: \omega \equiv \Omega_s - \Omega_c > 0$ 



$$
J = I_s \Omega_s + I_c \Omega_c \qquad E_{rot} =
$$

Garvin Yim High priority transient continuous gravitational wave targets At a glitch, the components couple and the superfluid component transfers angular momentum to the crustal component, leading to an observed glitch

- Summary: Excess rotational kinetic energy of two components  $\rightarrow E_{GW}$
- Two component model: superfluid (s) and crust+everything else coupled to it (c) 1 2  $I_s \Omega_s^2$  + 1 2  $I_c\Omega_c^2$

- 
- 





# Model 2: Vortex unpinning (two component) model

[Sidery et al. 2010, LSC 2011, Prix et al. 2011]

The superfluid component spins-down as the crustal component spins-up  $\Delta J = I_s \Delta \Omega_s + I_c \Delta \Omega_c = 0$ 





# Model 2: Vortex unpinning (two component) model

[Sidery et al. 2010, LSC 2011, Prix et al. 2011]

- 
- and they co-rotate after the glitch at  $\Omega_{co} = \Omega_{0,i} + \Delta\Omega_i$  for  $i = s, c$ .

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Summary: Excess rotational kinetic energy of two components  $\rightarrow E_{GW}$ 

- The superfluid component spins-down as the crustal component spins-up  $\Delta J = I_s \Delta \Omega_s + I_c \Delta \Omega_c = 0$
- and they co-rotate after the glitch at  $\Omega_{co} = \Omega_{0,i} + \Delta\Omega_i$  for  $i = s, c$ .
- We can calculate the resultant change in energy for each component  $\Delta E_{rot,i} =$ 1 2 *I<sub>i</sub>*[Ω<sup>2</sup><sub>co</sub> – (Ω<sub>co</sub> – ΔΩ<sub>*i*</sub>)<sup>2</sup>]

 $-1$ 

 $E_{GW}$  = 1 2 *I*(ΔΩ) 2 *Is*  $\left| \right|$ *I* ) −1

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Summary: Excess rotational kinetic energy of two components  $\rightarrow E_{GW}$ 

and when we sum the two components together, we get an excess energy of:

$$
\int_{1}^{1} \text{ where } I = I_{s} + I_{c}
$$





### Model 2: Vortex unpinning (two component) model [Sidery et al. 2010, LSC 2011, Prix et al. 2011]

## Model 3: Transient mountain model [Yim & Jones 2020, Moragues et al. 2023]

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Summary: Increase in  $|\dot{\nu}|$  due to mountain, present until  $|\dot{\nu}|$  recovers  $\dot{\nu}$  | due to mountain, present until |  $\dot{\nu}$  |





## Model 3: Transient mountain model [Yim & Jones 2020, Moragues et al. 2023]

Considers angular momentum conservation **·**<br>– **·**<br>– .<br>
<sup>-</sup> Glitch: Δ  $\Omega(t) = \Delta$  $\Omega_p + \Delta$  $\Omega_t(t) = \Delta$ 

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### Summary: Increase in  $|\dot{\nu}|$  due to mountain, present until  $|\dot{\nu}|$  recovers  $\dot{\nu}$  | due to mountain, present until |  $\dot{\nu}$  |

### $\Delta \nu$  ( $\mu$ Hz) .<br>.<br>. .<br>
<sup>•</sup>  $e^{-t}$  $\Omega_p + \Delta$  $\Omega_t$ *τEM*  $-3.735$  $\hat{V}$  (10<sup>-10</sup> Hz s<sup>-1</sup>)  $-3.740$  $-3.745$







### .<br>.<br>.  $\Omega_p + \Delta$ .<br>
<sup>•</sup>  $\Omega_t$  $e^{-t}$ *τEM*

*I*Δ **·**<br>?  $\dot{\Omega}_t(t) = -\frac{32}{5}$ 5 *G c*5  $I^2\Omega^5$ ε<sup>2</sup>(*t*)





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## Model 3: Transient mountain model [Yim & Jones 2020, Moragues et al. 2023]

- Considers angular momentum conservation **·**<br>– **·**<br>– .<br>
<sup>-</sup>
	- Glitch: Δ  $\Omega(t) = \Delta$  $\Omega_p + \Delta$  $\Omega_t(t) = \Delta$
	- Attribute the transient part to a transient mountain

## Model 3: Transient mountain model [Yim & Jones 2020, Moragues et al. 2023]

Considers angular momentum conservation **·**<br>– **·**<br>– .<br>
<sup>-</sup>

Glitch: Δ  $\Omega(t) = \Delta$  $\Omega_p + \Delta$  $\Omega_t(t) = \Delta$ 

*I*Δ **·**<br>?  $\dot{\Omega}_t(t) = -\frac{32}{5}$ 5 *G c*5  $I^2\Omega^5\varepsilon^2(t) \rightarrow \varepsilon(t) = \sqrt{\frac{5}{25}}$ 

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### Summary: Increase in  $|\dot{\nu}|$  due to mountain, present until  $|\dot{\nu}|$  recovers  $\dot{\nu}$  | due to mountain, present until |  $\dot{\nu}$  |

Attribute the transient part to a transient mountain 







### Model 3: Transient mountain model [Yim & Jones 2020, Moragues et al. 2023]  $\dot{\nu}$  | due to mountain, present until |  $\dot{\nu}$  | Summary: Increase in  $|\dot{\nu}|$  due to mountain, present until  $|\dot{\nu}|$  recovers Considers angular momentum conservation  $\Delta \nu$  ( $\mu$ Hz) **·**<br>– **·**<br>– .<br>
<sup>-</sup> .<br>.<br>. .<br>
<sup>•</sup>  $e^{-t}$ Glitch: Δ  $\Omega(t) = \Delta$  $\Omega_p + \Delta$  $\Omega_t(t) = \Delta$  $\Omega_p + \Delta$  $\Omega_t$ *τEM* Attribute the transient part to a transient mountain  $-3.735$  $\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$ <br>  $\begin{pmatrix} 10^{-10} & 3.740 \\ -3.745 & 1 \end{pmatrix}$ **·**<br>?  $c^5$  $\dot{\Omega}_t(t) = -\frac{32}{5}$ *G* Δ  $\Omega_t$  $I^2\Omega^5\varepsilon^2(t) \rightarrow \varepsilon(t) = \sqrt{\frac{5}{25}}$ 1 **·**<br>?  $\frac{dS_1}{Q_2}e^{-\frac{t}{2\tau_H}}$  $-3.750$ *I*Δ 2*τEM c*5 5 32 *G I*  $-50$  $-100$  $\overline{0}$ Days from  $MJD = 53067.1$  $N$ ote:  $h_0(t) \propto \varepsilon(t)$  so if  $h_0(t) \equiv h_0 e^{-\frac{t}{\tau_{GW}}}$  then  $\tau_{GW} = 2\tau_{EM}$







## Model 3: Transient mountain model [Yim & Jones 2020, Moragues et al. 2023]

 $L_{GW} =$ 

and integrate between  $t = 0$  and  $t \to \infty$  to find

where  $Q = \frac{1}{\sqrt{2}} = -\frac{1}{\sqrt{2}}$ .  $ΔΩ_t$ ΔΩ  $=-\frac{\Delta}{\sqrt{2\pi}}$ .<br>.<br>.  $\Omega_t$ *τEM*ΔΩ

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- Summary: Increase in  $|\dot{\nu}|$  due to mountain, present until  $|\dot{\nu}|$  recovers  $\dot{\nu}$  | due to mountain, present until |  $\dot{\nu}$  |
- Once  $\varepsilon$ (*t*) is obtained from torque balance, can substitute into GW luminosity



Analogous to "CW spin-down limit" but for glitches!





## Model 4: Ekman pumping model

[van Eysden & Melatos 2008, Bennett et al. 2010, Singh 2017]





## $η = 10^{-7} - 10^{-5}$  from simulations (Singh 2017)

### Summary: Tangential forces at a boundary of a viscous fluid causes (non-axisymmetric) meridional flows, sets up mass and current multipoles



Credit: Benton & Clark (1974)

 $E_{GW} = \eta I_{crust} \Omega \Delta \Omega$ 

## Model 5: Naïve (one component) model [Ho et al. 2020]

 $E_{GW} =$ 1 2  $I_s(\Omega_s^2 - \Omega_c^2) \rightarrow \frac{E_{GW}}{E_{GW}} = I\Omega \Delta \Omega$ 

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- Summary: 100% rotational kinetic energy from glitch  $\rightarrow E_{GW}$ 
	- $E_{GW} = I\Omega\Delta\Omega$  : (Assumes  $\Delta I = 0$ , unlike starquake model)
- Model 6: Naïve (two component) model [Prix et al. 2011, Moragues et al. 2023]
	- Summary: Reservoir of rotational kinetic energy in superfluid  $component$  if  $\Omega_{c} > \Omega_{c}$ 
		-
- Both agnostic models provide an "upper energy limit" for glitches!





where *κ* is defined as  $E_{GW} = \kappa I \Omega^2$  $\left\{ \right.$ ΔΩ Ω )



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# Summary table



where *κ* is defined as  $E_{GW} = \kappa I \Omega^2$  $\left\{ \right.$ ΔΩ Ω )

# Summary table







Part II - Gravitational wave signal analysis



# Signal-to-noise ratio in terms of  $E_{GW}$  [Prix et al. 2011]

- the signal-to-noise ratio (SNR)  $\rho$  in terms of  $E_{GW}$ .
- 

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Now that we have  $E_{GW}$  for different models, we need to find a way to express

The SNR is defined as:  $\rho = \sqrt{(h|h)}$  where  $(a|b) = 4Re$ ∞  $\bf{0}$ *a* ˜(*f*)*b*  $\tilde{b}$ \*(*f*) *Sn*(*f*) *df*







## Signal-to-noise ratio in terms of  $E_{GW}$  [Prix et al. 2011] Now that we have  $E_{GW}$  for different models, we need to find a way to express the signal-to-noise ratio (SNR)  $\rho$  in terms of  $E_{GW}$ . The SNR is defined as:  $\rho = \sqrt{(h|h)}$  where  $(a|b) = 4Re$ *Polarisation:*  $h(t) = F_+(t)h_+(t) + F_x(t)h_x(t)$  where  $h_{+,x}(t) = h_0(t) f_{+,x}(\theta, t; t)$ ∞  $\bf{0}$ *a* ˜(*f*)*b*  $\tilde{b}$

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\*(*f*) *Sn*(*f*) *df*





### Signal-to-noise ratio in terms of  $E_{GW}$  [Prix et al. 2011] Now that we have  $E_{GW}$  for different models, we need to find a way to express the signal-to-noise ratio (SNR)  $\rho$  in terms of  $E_{GW}$ . The SNR is defined as:  $\rho = \sqrt{(h|h)}$  where  $(a|b) = 4Re$ Polarisation:  $h(t) = F_+(t)h_+(t) + F_+(t)h_+(t)$  where  $h_{+,x}(t) = h_0(t) f_-(t)$ ∞  $\bf{0}$ *a* ˜(*f*)*b*  $\tilde{b}$  $\rightarrow$   $\rho^2 = \beta$ 1 *Sn*(*f*) ∫ *Tobs* 0  $h_0^2(t)dt$   $\beta = 1$  if  $F_{+x} = \frac{1}{\sqrt{2}}$  (constant),  $\theta = \frac{\pi}{2}$  and 1 2  $\theta =$ *π* 2  $l = 0$  $\beta = \frac{1}{25}$  if sky and orientation averaged 4 25

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(*h*) where 
$$
(a|b) = 4Re\left(\int_0^\infty \frac{\tilde{a}(f)\tilde{b}^*(f)}{S_n(f)} df\right)
$$



$$
t)h_{\mathsf{x}}(t) \quad \text{where} \quad h_{+,\mathsf{x}}(t) = h_0(t) \, f_{+,\mathsf{x}}(\theta, t; t)
$$

$$
\beta = 1 \text{ if } F_{+,\times} = \frac{1}{\sqrt{2}} \text{ (constant)}, \theta = \frac{\pi}{2} \text{ and } t = 0
$$

[Jarankowski, Królak & Schutz 1998]



### Signal-to-noise ratio in terms of  $E_{GW}$  [Prix et al. 2011] Now that we have  $E_{GW}$  for different models, we need to find a way to express the signal-to-noise ratio (SNR)  $\rho$  in terms of  $E_{GW}$ . The SNR is defined as:  $\rho = \sqrt{(h|h)}$  where  $(a|b) = 4Re$ Polarisation:  $h(t) = F_+(t)h_+(t) + F_+(t)h_+(t)$  where  $h_{+,x}(t) = h_0(t) f_-(t)$ ∞  $\bf{0}$ *a* ˜(*f*)*b*  $\tilde{b}$  $\rightarrow$   $\rho^2 = \beta$ 1 *Sn*(*f*) ∫ *Tobs* 0  $h_0^2(t)dt$   $\beta = 1$  if  $F_{+x} = \frac{1}{\sqrt{2}}$  (constant),  $\theta = \frac{\pi}{2}$  and 1 2  $\theta =$ *π* 2  $l = 0$ 4

$$
(h) \quad \text{where} \quad (a \mid b) = 4\text{Re}\left(\int_0^\infty \frac{\tilde{a}(f)\tilde{b}^*(f)}{S_n(f)} df\right)
$$

 $\beta = \frac{1}{25}$  if sky and orientation averaged 25 [Jarankowski, Królak & Schutz 1998]



$$
t)h_{\mathsf{x}}(t) \quad \text{where} \quad h_{+,\mathsf{x}}(t) = h_0(t) \, f_{+,\mathsf{x}}(\theta, t; t)
$$

$$
\beta = 1 \text{ if } F_{+,x} = \frac{1}{\sqrt{2}} \text{ (constant), } \theta = \frac{\pi}{2} \text{ and } \iota = 0
$$

But for targeted searches, we can do better. We can, and should, incorporate information about sky position.



$$
(h) \quad \text{where} \quad (a \mid b) = 4\text{Re}\left(\int_0^\infty \frac{\tilde{a}(f)\tilde{b}^*(f)}{S_n(f)} df\right)
$$

 $\beta = \frac{1}{25}$  if sky and orientation averaged 4 25 [Jarankowski, Królak & Schutz 1998]





Now that we have  $E_{GW}$  for different models, we need to find a way to express

$$
t)h_{\mathsf{x}}(t) \quad \text{where} \quad h_{+,\mathsf{x}}(t) = h_0(t) \, f_{+,\mathsf{x}}(\theta, t; t)
$$

$$
h_0^2(t)dt
$$
  $\beta = 1$  if  $F_{+,x} = \frac{1}{\sqrt{2}}$  (constant),  $\theta = \frac{\pi}{2}$  and  $t = 0$ 

But for targeted searches, we can do better. We can, and should, incorporate





# Transient CW approximation

which was done in JKS.

Comparing to our earlier expression, we find:  $\beta = A_2(\delta, \psi, \iota, \lambda, \gamma)$ 

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- Ideally, we want to discard the  $B_2$  term. One could do so by averaging over  $\alpha$ ,
- Here, we note that for sufficiently long  $T_{obs}$ , the  $A_2T_{obs}$  term will dominate:

 $\rho^2 = [A_2(\delta, \psi, \iota, \lambda, \gamma)T_{obs} + B_2(\alpha, \delta, \psi, \iota, \lambda, \gamma; T_{obs})] - \frac{h_0^2}{g}$ 0 *Sn*(*f*)

 $\rightarrow$   $\rho^2 = A_2(\delta, \psi, \iota, \lambda, \gamma)$  $h_0^2 T_{obs}$ *Sn*(*f*)





# Quantifying the error





# $max(T_{thres})$  as a function of  $\delta$



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Error in SNR will be less than 10% for all (*α*, *δ*) so long as *Tobs* > 1.74 d









## Data information

(naïve, vortex unpinning, transient mountain).

: 686 glitches from 219 pulsars : 132 glitches from 57 pulsars  $\left\{ \right.$ ΔΩ  $\overline{\Omega}$ <sup>, *d*</sup>  $\begin{array}{c} \hline \end{array}$  $\left\langle \right\rangle$ ΔΩ  $\overline{\Omega}$ , Q, d  $\begin{array}{c} \hline \end{array}$ 





$$
E_{GW} \rightarrow \frac{\Delta \Omega}{\Omega}, Q, \frac{I_s}{I}
$$
  

$$
\rho \rightarrow \Omega, d, S_n(f)
$$

$$
\rho^2 = \frac{5A_2 G}{2\pi^2 c^3} \frac{1}{S_n(f)} \frac{E_{GW}}{f^2 d^2}
$$

 $S_n(f)$  = Hanford, Livingston and Virgo in O4

JBCA Glitch Catalogue: 
$$
\frac{\Delta \Omega}{\Omega}
$$
ATNF Glitch Table: 
$$
\frac{\Delta \Omega}{\Omega}
$$
, 
$$
\rho
$$

ATNF Pulsar Catalogue: Ω, d

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# We can now analytically approximate the SNR from the different models

# SNR histograms



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### Naïve Vortex unpinning Transient mountain



# Top 15 targets for naïve models



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### Naïve models





# Top 15 targets for vortex unpinning model



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### Vortex unpinning model





# Top 15 targets for transient mountain model

### Transient mountain model





-mode calculation (Yim *f* & Jones 2023) gives:  $\rho = 50, 25, 7$ , for Livingston, Hanford and Virgo (but using  $\beta = 1$ )









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# itched on 29th April 2024!

1, 16615, 16619 20:52:18.1



## erving during glitch

**Transient mountain**  $2.4 \times 10^{42}$ 

Part IV - Summary



# Summary

- The SNR of a transient CW source can be estimated by obtaining  $E_{GW}$ .
- We explored 6 different models associated with pulsar glitches.
- For a sufficiently long transient CW, we can make a better estimate of the SNR by including information about the pulsar's sky position.
- In O4, we will start putting upper limits on some of these models. As shown, this can already be done with Vela's latest glitch!
	- Must start considering what physics can be learnt from a (non-)detection: superfluidity, elasticity/plastic flow, viscosity, magnetic diffusion, temperature gradients, etc…





# Continuous Waves School at KIAA, Beijing

- 7th 11th July
- Invited lecturers:
	- Prof. Maria Alessandra Papa (Albert Einstein Institute)  $\psi$
	- Prof. Ian Jones (University of Southampton)
	- Dr. David Keitel (University of the Balearic Islands)  $\psi$
	- Dr. Lilli Sun (Australian National University)
	- Plus 6 guest speakers
	- Speak with me if you are interested!
	- Email: [g.yim@pku.edu.cn](mailto:g.yim@pku.edu.cn)
- Website: <https://garvinyim.wixsite.com/home/cw-school-at-kiaa>
- Hungary, Austria, Belgium, Luxembourg, Malaysia, Brunei, Singapore.

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Visa-free nationalities: France, Germany, Italy, the Netherlands, Spain, Switzerland, Ireland,





