High priority targets for transient continuous waves from glitching pulsars

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Yim, Shao & Xu (submitted), arXiv: 2406.00283 CWs Workshop, AEI, 16th June 2024



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Contents

- Objectives:

 Compare different pulsar glitch models Create a list of high priority targets

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Not yet observed a continuous gravitational wave (CW) signal

Part I - Energy budgets from pulsar glitches Part II - Gravitational wave signal analysis Part III - Results Part IV - Summary







Part I - Energy budgets from pulsar glitches



Transient continuous waves

Duration = $\mathcal{O}(Minutes)$



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Duration \gg Observation time



Duration





Transient continuous waves

Transient Continuous Waves

Duration = $\mathcal{O}(Minutes)$



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 $h(t) = \varpi(t; t_0, T_{GW})h_{CW}(t)$

O(Minutes) < Duration < *O*(Months)

Duration \gg Observation time



Duration







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"Glitch rise" models

Model 1: Starquake (one component)

Model 2: Superfluid vortex unpinning (two components)



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"Postglitch" models Model 3: Transient mountain Model 4: Ekman pumping





"Glitch rise" models

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"Postglitch" models
Model 3: Transient mountain
Model 4: Ekman pumping

Glitch models attempt to explain the spin-up. Postglitch models are agnostic to what causes the spin-up.





+2 "naïve" models, one each for oneand two- component neutron stars

"Glitch rise" models

Model 1: Starquake (one component)

Model 2: Superfluid vortex unpinning (two components)



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Credit: Espinoza et al. (2011)

"Postglitch" models Model 3: Transient mountain

Model 4: Ekman pumping

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+2 "naïve" models, one each for oneand two- component neutron stars

"Glitch rise" models

Model 1: Starquake (one component)

Model 2: Superfluid vortex unpinning (two components)

> Concerned mostly about the energy available for GW emission, E_{GW}



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Credit: Espinoza et al. (2011)

"Postglitch" models Model 3: Transient mountain

Model 4: Ekman pumping

Glitch models attempt to explain the spin-up. Postglitch models are agnostic to what causes the spin-up.





Model 1: Starquake (one component) model

[Sidery et al. 2010, LSC 2011]

Summary: Reduction in ΔI leads to an increase in $\Delta \Omega$ since $\Delta J = 0$

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kinetic energy can be written as: $J = I\Omega$ and $E_{rot} = I\Omega^2/2$

One component in the sense that the angular momentum and rotational







Model 1: Starquake (one component) model [Sidery et al. 2010, LSC 2011]

- One component in the sense that the angular momentum and rotational kinetic energy can be written as: $J = I\Omega$ and $E_{rot} = I\Omega^2/2$
- Imagine a sudden decrease in the moment of inertia ΔI , i.e. a starquake.
- We must conserve angular momentum so $\Delta J \approx (\Delta I)\Omega + I\Delta\Omega = 0$
 - This causes the energy to change: $\Delta E_{rot} = \frac{1}{2}(I + \Delta I)(\Omega + \Delta \Omega)^2 \frac{1}{2}I\Omega^2$

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Assuming $E_{GW} = \Delta E_{rot}$ this means

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Summary: Reduction in ΔI leads to an increase in $\Delta \Omega$ since $\Delta J = 0$

$$\Delta E_{rot} = \frac{1}{2} (I + \Delta I)(\Omega + \Delta \Omega)^2 - \frac{1}{2} I \Omega^2$$

$$E_{GW} = \frac{1}{2} I \Omega \Delta \Omega$$





[Sidery et al. 2010, LSC 2011, Prix et al. 2011]

Summary: Excess rotational kinetic energy of two components $\rightarrow E_{GW}$

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[Sidery et al. 2010, LSC 2011, Prix et al. 2011]

Summary: Excess rotational kinetic energy of two components $\rightarrow E_{GW}$

Two component model: superfluid (s) and crust+everything else coupled to it (c)

 $J = I_s \Omega_s + I_c \Omega_c \qquad E_{rot}$

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 $E_{rot} = \frac{1}{2}I_s\Omega_s^2 + \frac{1}{2}I_c\Omega_c^2$



[Sidery et al. 2010, LSC 2011, Prix et al. 2011]

$$J = I_s \Omega_s + I_c \Omega_c \qquad \qquad E_{rot} =$$

External torque (e.g. magnetic dipole radiation) acts only on the crust component, so lag develops between the two components: $\omega \equiv \Omega_s - \Omega_c > 0$

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- Summary: Excess rotational kinetic energy of two components $\rightarrow E_{GW}$
- Two component model: superfluid (s) and crust+everything else coupled to it (c) $=\frac{1}{2}I_s\Omega_s^2 + \frac{1}{2}I_c\Omega_c^2$







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$$J = I_s \Omega_s + I_c \Omega_c \qquad \qquad E_{rot} =$$

- External torque (e.g. magnetic dipole radiation) acts only on the crust component, so lag develops between the two components: $\omega \equiv \Omega_s - \Omega_c > 0$
- At a glitch, the components couple and the superfluid component transfers angular momentum to the crustal component, leading to an observed glitch High priority transient continuous gravitational wave targets Garvin Yim

- Summary: Excess rotational kinetic energy of two components $\rightarrow E_{GW}$
- Two component model: superfluid (s) and crust+everything else coupled to it (c) $=\frac{1}{2}I_s\Omega_s^2 + \frac{1}{2}I_c\Omega_c^2$







Model 2: Vortex unpinning (two component) model [Sidery et al. 2010, LSC 2011, Prix et al. 2011]

- - and they co-rotate after the glitch at $\Omega_{co} = \Omega_{0,i} + \Delta \Omega_i$ for i = s, c.

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Summary: Excess rotational kinetic energy of two components $\rightarrow E_{GW}$

The superfluid component spins-down as the crustal component spins-up $\Delta J = I_{c} \Delta \Omega_{c} + I_{c} \Delta \Omega_{c} = 0$





Model 2: Vortex unpinning (two component) model [Sidery et al. 2010, LSC 2011, Prix et al. 2011]

- The superfluid component spins-down as the crustal component spins-up $\Delta J = I_{\rm s} \Delta \Omega_{\rm s} + I_{\rm c} \Delta \Omega_{\rm c} = 0$
 - and they co-rotate after the glitch at $\Omega_{co} = \Omega_{0,i} + \Delta \Omega_i$ for i = s, c.
- We can calculate the resultant change in energy for each component $\Delta E_{rot,i} = \frac{1}{2} I_i [\Omega_{co}^2 - (\Omega_{co} - \Delta \Omega_i)^2]$

$$E_{GW} = \frac{1}{2} I(\Delta \Omega)^2 \left(\left(\frac{I_s}{I} \right)^{-1} \right)^{-1}$$

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Summary: Excess rotational kinetic energy of two components $\rightarrow E_{GW}$

and when we sum the two components together, we get an excess energy of:

where
$$I = I_s + I_c$$





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Considers angular momentum conservation Glitch: $\Delta \dot{\Omega}(t) = \Delta \dot{\Omega}_p + \Delta \dot{\Omega}_t(t) = \Delta \dot{\Omega}_p + \Delta \dot{\Omega}_t e^{-\frac{t}{\tau_{EM}}}$

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Summary: Increase in $|\dot{\nu}|$ due to mountain, present until $|\dot{\nu}|$ recovers

Δu (μ Hz) -3.735 -3.740 -3.745 -3.750







- Considers angular momentum conservation
 - Glitch: $\Delta \dot{\Omega}(t) = \Delta \dot{\Omega}_p + \Delta \dot{\Omega}_t(t) = \Delta \dot{\Omega}_p + \Delta \dot{\Omega}_t e^{-\frac{t}{\tau_{EM}}}$
 - Attribute the transient part to a transient mountain

 $I\Delta\dot{\Omega}_t(t) = -\frac{32}{5}\frac{G}{c^5}I^2\Omega^5\varepsilon^2(t)$

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Considers angular momentum conservation

Glitch: $\Delta \dot{\Omega}(t) = \Delta \dot{\Omega}_p + \Delta \dot{\Omega}_t(t) = \Delta \dot{\Omega}_p + \Delta \dot{\Omega}_t e^{-\frac{t}{\tau_{EM}}}$

Attribute the transient part to a transient mountain stiller,

 $I\Delta\dot{\Omega}_{t}(t) = -\frac{32}{5}\frac{G}{c^{5}}I^{2}\Omega^{5}\varepsilon^{2}(t) \rightarrow \varepsilon(t) = \sqrt{-\frac{5}{32}\frac{c^{5}}{G}\frac{1}{L}\frac{\Delta\dot{\Omega}_{t}}{\Omega^{5}}}e^{-\frac{t}{2\tau_{EM}}}$

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- Considers angular momentum conservation
 - Glitch: $\Delta \dot{\Omega}(t) = \Delta \dot{\Omega}_p + \Delta \dot{\Omega}_t(t) = \Delta \dot{\Omega}_p + \Delta \dot{\Omega}_t e^{-\frac{t}{\tau_{EM}}}$
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$$I\Delta\dot{\Omega}_{t}(t) = -\frac{32}{5}\frac{G}{c^{5}}I^{2}\Omega^{5}\varepsilon^{2}(t) \quad \rightarrow \quad \varepsilon(t) =$$

Note: $h_0(t) \propto \varepsilon(t)$ so if $h_0(t) \equiv h_0 e^{-\frac{t}{\tau_{GW}}}$ then $\tau_{GW} = 2\tau_{EM}$

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and integrate between t = 0 and $t \rightarrow \infty$ to find

where Q $au_{EM}\Delta\Omega$ $\Delta \Omega$

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- Summary: Increase in $|\dot{\nu}|$ due to mountain, present until $|\dot{\nu}|$ recovers
- Once $\varepsilon(t)$ is obtained from torque balance, can substitute into GW luminosity



Analogous to "CW spin-down limit" but for glitches!





Model 4: Ekman pumping model

[van Eysden & Melatos 2008, Bennett et al. 2010, Singh 2017]

Summary: Tangential forces at a boundary of a viscous fluid causes (non-axisymmetric) meridional flows, sets up mass and current multipoles



Credit: Benton & Clark (1974)

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 $E_{GW} = \eta I_{crust} \Omega \Delta \Omega$

$\eta = 10^{-7} - 10^{-5}$ from simulations (Singh 2017)





Model 5: Naïve (one component) model [Ho et al. 2020]

 $E_{GW} = I\Omega\Delta\Omega$

 $E_{GW} = \frac{1}{2} I_s (\Omega_s^2 - \Omega_c^2) \rightarrow E_{GW} = I \Omega \Delta \Omega$

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- Summary: 100% rotational kinetic energy from glitch $\rightarrow E_{GW}$
 - (Assumes $\Delta I = 0$, unlike starquake model)
- Model 6: Naïve (two component) model [Prix et al. 2011, Moragues et al. 2023]
 - Summary: Reservoir of rotational kinetic energy in superfluid component if $\Omega_{s} > \Omega_{c}$
- Both agnostic models provide an "upper energy limit" for glitches!





Summary table

	(Glitch rise	Post-gl	litch	Naïve		
	Starquake	Vortex unpinning	Transient mountain	Ekman pumping	One component	Two components	
$E_{\rm GW}$	$rac{1}{2}I\Omega\Delta\Omega$	$\frac{1}{2}I(\Delta\Omega)^2\left(\frac{I}{I_{\rm p}}-1\right)$	$QI\Omega\Delta\Omega$	$2\pi\rho_0\Gamma L^5\eta\Omega\Delta\Omega$	$I\Omega\Delta\Omega$	$I\Omega\Delta\Omega$	
κ	$\frac{1}{2}$	$\frac{1}{2} \left(\frac{\Delta\Omega}{\Omega}\right) \left(\frac{I}{I_{\rm p}} - 1\right)$	Q	$\eta rac{I_{ ext{crust}}}{I}$	1	1	

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where κ is defined as $E_{GW} = \kappa I \Omega^2 \left(\frac{\Delta \Omega}{\Omega}\right)$





Summary table

		Glitch rise	Post-g	litch	Naïve		
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$E_{\rm GW}$	$rac{1}{2}I\Omega\Delta\Omega$	$\frac{1}{2}I(\Delta\Omega)^2\left(\frac{I}{I_{\rm p}}-1\right)$	$QI\Omega\Delta\Omega$	$2\pi\rho_0\Gamma L^5\eta\Omega\Delta\Omega$	$I\Omega\Delta\Omega$	$I\Omega\Delta\Omega$	
κ	$\frac{1}{2}$	$\frac{1}{2} \left(\frac{\Delta \Omega}{\Omega}\right) \left(\frac{I}{I_{\rm p}} - 1\right)$	Q	$\eta rac{I_{ ext{crust}}}{I}$	1	1	

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where κ is defined as $E_{GW} = \kappa I \Omega^2 \left(\frac{\Delta \Omega}{\Omega}\right)$





Part II - Gravitational wave signal analysis



Signal-to-noise ratio in terms of E_{GW} [Prix et al. 2011]

- the signal-to-noise ratio (SNR) ρ in terms of E_{GW} .



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Now that we have E_{GW} for different models, we need to find a way to express

The SNR is defined as: $\rho = \sqrt{(h|h)}$ where $(a|b) = 4\text{Re}\left(\int_0^\infty \frac{\tilde{a}(f)\tilde{b}^*(f)}{S_n(f)}df\right)$







Signal-to-noise ratio in terms of E_{GW} [Prix et al. 2011] Now that we have E_{GW} for different models, we need to find a way to express the signal-to-noise ratio (SNR) ρ in terms of E_{GW} .

- Polarisation: $h(t) = F_+(t)h_+(t) + F_{\times}(t)h_{\times}(t)$ where $h_{+,\times}(t) = h_0(t)f_{+,\times}(\theta, t; t)$

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Signal-to-noise ratio in terms of E_{GW} [Prix et al. 2011] Now that we have E_{GW} for different models, we need to find a way to express the signal-to-noise ratio (SNR) ρ in terms of E_{GW} . The SNR is defined as: $\rho = \sqrt{h}$ Polarisation: $h(t) = F_+(t)h_+(t) + F_{x}(t)$ $\rightarrow \rho^2 = \beta \frac{1}{S_n(f)} \int_0^{T_{obs}} h_0^2(t) dt$ $\beta = \frac{4}{25}$ if sky and orientation averaged

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$$\overline{|h|}$$
 where $(a|b) = 4\text{Re}\left(\int_{0}^{\infty} \frac{\tilde{a}(f)\tilde{b}^{*}(f)}{S_{n}(f)}df\right)$

$$t)h_{\mathsf{X}}(t)$$
 where $h_{+,\mathsf{X}}(t) = h_0(t) f_{+,\mathsf{X}}(\theta, \iota; t)$

$$\beta = 1$$
 if $F_{+,\times} = \frac{1}{\sqrt{2}}$ (constant), $\theta = \frac{\pi}{2}$ and $\iota = 0$

[Jarankowski, Królak & Schutz 1998]



Signal-to-noise ratio in terms of E_{GW} [Prix et al. 2011] Now that we have E_{GW} for different models, we need to find a way to express the signal-to-noise ratio (SNR) ρ in terms of E_{GW} . • The SNR is defined as: $\rho = \sqrt{(h)}$ Polarisation: $h(t) = F_+(t)h_+(t) + F_{\times}(t)$ $\rightarrow \rho^2 = \beta \frac{1}{S_n(f)} \int_0^{T_{obs}} h_0^2(t) dt$

But for targeted searches, we can do better. We can, and should, incorporate information about sky position.

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Signal-to-noise ratio in terms of E_{GW} [Prix et al. 2011] Now that we have E_{GW} for different models, we need to find a way to express the signal-to-noise ratio (SNR) ρ in terms of E_{GW} . • The SNR is defined as: $\rho = \sqrt{(h)}$ • Polarisation: $h(t) = F_+(t)h_+(t) + F_{\times}(t)$ $\rightarrow \rho^2 = \beta \frac{1}{S_n(f)} \int_0^{T_{obs}} h_0^2(t) dt$ $\rightarrow \rho^2 = \frac{5\beta}{2\pi^2} \frac{G}{c^3} \frac{1}{S_p(f)} \frac{E_{GW}}{f^2 d^2}$ $\beta = \frac{4}{25}$ if sky and orientation averaged But for targeted searches, we can do better. We can, and should, incorporate information about sky position. Garvin Yim High priority transient continuous gravitational wave targets 12/23

$$\overline{|h|}$$
 where $(a|b) = 4\text{Re}\left(\int_{0}^{\infty} \frac{\tilde{a}(f)\tilde{b}^{*}(f)}{S_{n}(f)}df\right)$

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 if $F_{+,\times} = \frac{1}{\sqrt{2}}$ (constant), $\theta = \frac{\pi}{2}$ and $\iota = 0$

[Jarankowski, Królak & Schutz 1998]







Transient CW approximation

 $\rho^{2} = \left[A_{2}(\delta, \psi, \iota, \lambda, \gamma)T_{obs} + B_{2}(\alpha, \delta, \psi, \iota, \lambda, \gamma; T_{obs})\right] \frac{h_{0}^{2}}{S(f)}$

which was done in JKS.

Comparing to our earlier expression, we find: $\beta = A_2(\delta, \psi, \iota, \lambda, \gamma)$

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- Ideally, we want to discard the B_2 term. One could do so by averaging over α ,
- Here, we note that for sufficiently long $T_{obs'}$ the A_2T_{obs} term will dominate:

 $\rightarrow \rho^2 = A_2(\delta, \psi, \iota, \lambda, \gamma) \frac{h_0^2 T_{obs}}{S_n(f)}$

Quantifying the error

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$\max(T_{thres})$ as a function of δ

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Error in SNR will be less than 10% for <u>all</u> (α, δ) so long as $T_{obs} > 1.74 \text{ d}$

Part III - Results

Data information

(naïve, vortex unpinning, transient mountain).

$$E_{GW} \rightarrow \frac{\Delta\Omega}{\Omega}, Q, \frac{I_s}{I}$$

$$\rho \rightarrow \Omega, d, S_p(f)$$

JBCA Glitch Catalogue:
$$\frac{\Delta\Omega}{\Omega}$$

ATNF Glitch Table: $\frac{\Delta\Omega}{\Omega}$, Q

ATNF Pulsar Catalogue: Ω , d

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We can now analytically approximate the SNR from the different models

$$\rho^2 = \frac{5A_2}{2\pi^2} \frac{G}{c^3} \frac{1}{S_n(f)} \frac{E_{GW}}{f^2 d^2}$$

 $S_n(f)$ = Hanford, Livingston and Virgo in O4

$$\left(\frac{\Delta\Omega}{\Omega}, d\right)$$
: 686 glitches from 219 pulsars
 $\left(\frac{\Delta\Omega}{\Omega}, Q, d\right)$: 132 glitches from 57 pulsars

SNR histograms

Naïve

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Vortex unpinning

Transient mountain

Top 15 targets for naïve models

Pulsar J-name	α [°]	δ [°]	$\nu \; [Hz]$	$\dot{\nu} \; [\text{Hz s}^-1]$	$d \; [\mathrm{kpc}]$	$N_{ m g}$	$\Delta \nu / \nu \ [10^{-9}]$	$\Delta \dot{\nu} / \dot{\nu} \ [10^{-3}]$	$E_{\rm GW}$ [erg]	$\max(ho)$
J0835-4510	128.84	-45.18	11.195	-1.57×10^{-11}	0.280	24	3100	148	1.53×10^{43}	156.3
J0940 - 5428	145.24	-54.48	11.423	-4.29×10^{-12}	0.377	2	1573.9	11	$8.11 imes 10^{42}$	95.9
J1952 + 3252	298.24	32.88	25.296	-3.74×10^{-12}	3.000	6	1489.9	5.4	3.76×10^{43}	38.5
J0205 + 6449	31.41	64.83	15.217	-4.49×10^{-11}	3.200	9	3800	12	3.47×10^{43}	36.6
J1813 - 1246	273.35	-12.77	20.802	-7.60×10^{-12}	2.635	1	1166	6.4	$1.99 imes 10^{43}$	34.3
J2229 + 6114	337.27	61.24	19.362	-2.90×10^{-11}	3.000	9	1223.6	13	1.81×10^{43}	30.9
J1105 - 6107	166.36	-61.13	15.822	-3.97×10^{-12}	2.360	5	971.7	0.1	9.60×10^{42}	26.1
J0534+2200	83.63	22.01	29.947	-3.78×10^{-10}	2.000	30	516.37	6.969	1.83×10^{43}	24.0
J1028 - 5819	157.12	-58.32	10.941	-1.93×10^{-12}	1.423	1	2296.5	35	1.09×10^{43}	23.9
J1524 - 5625	231.21	-56.42	12.785	-6.37×10^{-12}	3.378	1	2977	15.5	1.92×10^{43}	22.5
J1531 - 5610	232.87	-56.18	11.876	-1.95×10^{-12}	2.841	1	2637	25	1.47×10^{43}	20.0
J1112 - 6103	168.06	-61.06	15.394	-7.45×10^{-12}	4.464	4	1825	4.7	1.71×10^{43}	18.3
J1617 - 5055	244.37	-50.92	14.418	-2.81×10^{-11}	4.743	6	2068	13.2	1.70×10^{43}	16.0
J1420 - 6048	215.03	-60.80	14.667	-1.79×10^{-11}	5.632	7	2019	6.6	1.71×10^{43}	13.9
J1809 - 1917	272.43	-19.29	12.084	-3.73×10^{-12}	3.268	1	1625.1	7.8	9.37×10^{42}	13.6

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Naïve models

Top 15 targets for vortex unpinning model

Pulsar J-name	$\alpha ~[^{\circ}]$	δ [°]	$\nu \; [Hz]$	$\dot{\nu} \; [{ m Hz \; s^-1}]$	$d \; [\mathrm{kpc}]$	$N_{ m g}$	$\Delta \nu / \nu \ [10^{-9}]$	$\Delta \dot{\nu} / \dot{\nu} \ [10^{-3}]$	$E_{\rm GW}$ [erg]	$\max(ho)$
J0835-4510	128.84	-45.18	11.195	-1.57×10^{-11}	0.280	24	3100	148	2.35×10^{39}	1.94
J0940 - 5428	145.24	-54.48	11.423	-4.29×10^{-12}	0.377	2	1573.9	11	6.32×10^{38}	0.85
J0205 + 6449	31.41	64.83	15.217	-4.49×10^{-11}	3.200	9	3800	12	$6.53 imes 10^{39}$	0.50
J1952 + 3252	298.24	32.88	25.296	-3.74×10^{-12}	3.000	6	1489.9	5.4	2.78×10^{39}	0.33
J1524 - 5625	231.21	-56.42	12.785	-6.37×10^{-12}	3.378	1	2977	15.5	2.83×10^{39}	0.27
J1813 - 1246	273.35	-12.77	20.802	-7.60×10^{-12}	2.635	1	1166	6.4	1.15×10^{39}	0.26
J1028 - 5819	157.12	-58.32	10.941	-1.93×10^{-12}	1.423	1	2296.5	35	$1.23 imes 10^{39}$	0.25
J2229 + 6114	337.27	61.24	19.362	-2.90×10^{-11}	3.000	9	1223.6	13	$1.10 imes10^{39}$	0.24
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J1105 - 6107	166.36	-61.13	15.822	-3.97×10^{-12}	2.360	5	971.7	0.1	4.62×10^{38}	0.18
J1112 - 6103	168.06	-61.06	15.394	-7.45×10^{-12}	4.464	4	1825	4.7	$1.54 imes 10^{39}$	0.17
J1617 - 5055	244.37	-50.92	14.418	-2.81×10^{-11}	4.743	6	2068	13.2	1.74×10^{39}	0.16
J1420 - 6048	215.03	-60.80	14.667	-1.79×10^{-11}	5.632	7	2019	6.6	$1.71 imes 10^{39}$	0.14
J1809 - 1917	272.43	-19.29	12.084	-3.73×10^{-12}	3.268	1	1625.1	7.8	$7.54 imes 10^{38}$	0.12
J0534+2200	83.63	22.01	29.947	-3.78×10^{-10}	2.000	30	516.37	6.969	4.67×10^{38}	0.12

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High priority transient continuous gravitational wave targets

Vortex unpinning model

Top 15 targets for transient mountain model

Transient mountain model

Pulsar J-name	α [°]	δ [°]	$\nu [{\rm Hz}]$	$\dot{\nu} \; [\text{Hz s}^-1]$	$d \; [\mathrm{kpc}]$	$N_{ m g}$	$\Delta \nu / \nu \ [10^{-9}]$	$\Delta \dot{\nu} / \dot{\nu} \left[10^{-3} \right]$	Q	$E_{\rm GW}$ [erg]	$\max(ho)$
J0835-4510	128.84	-45.18	11.195	-1.57×10^{-11}	0.280	24	1805.2	77	0.1684	1.50×10^{42}	48.9
J0205 + 6449	31.41	64.83	15.217	-4.49×10^{-11}	3.200	9	5400	52	0.77	$3.80 imes 10^{43}$	38.3
J0534+2200	83.63	22.01	29.947	-3.78×10^{-10}	2.000	30	81	3.4	0.894	2.56×10^{42}	9.0
J0940 - 5428	145.24	-54.48	11.423	-4.29×10^{-12}	0.377	2	1573.9	11	0.0068	5.51×10^{40}	7.9
J1617 - 5055	244.37	-50.92	14.418	-2.81×10^{-11}	4.743	6	334	13	0.975	2.67×10^{42}	6.4
J1028 - 5819	157.12	-58.32	10.941	-1.93×10^{-12}	1.423	1	2296.5	35	0.0114	1.24×10^{41}	2.6
J1112 - 6103	168.06	-61.06	15.394	-7.45×10^{-12}	4.464	4	1202	7	0.022	2.47×10^{41}	2.2
J1524 - 5625	231.21	-56.42	12.785	-6.37×10^{-12}	3.378	1	2977.1	15.6	0.0058	1.11×10^{41}	1.7
J1531 - 5610	232.87	-56.18	11.876	-1.95×10^{-12}	2.841	1	2637	25	0.007	1.03×10^{41}	1.7
J1420 - 6048	215.03	-60.80	14.667	-1.79×10^{-11}	5.632	7	2019	6.6	0.008	1.37×10^{41}	1.2
J1809 - 1917	272.43	-19.29	12.084	-3.73×10^{-12}	3.268	1	1625.1	7.8	0.00602	5.64×10^{40}	1.1
J1302 - 6350	195.70	-63.84	20.937	-9.99×10^{-13}	2.632	1	2.3		0.36	1.43×10^{40}	1.0
J1837 - 0604	279.43	-6.08	10.383	-4.84×10^{-12}	4.779	3	1376	8	0.06	$3.51 imes 10^{41}$	0.9
J1709 - 4429	257.43	-44.49	9.760	-8.86×10^{-12}	2.600	5	2872	8	0.0129	$1.39 imes 10^{41}$	0.8
J1826 - 1334	276.55	-13.58	9.853	-7.31×10^{-12}	3.606	7	3581	9.6	0.0066	$9.06 imes 10^{40}$	0.5

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High priority transient continuous gravitational wave targets

B	reaking news: Vela gli
Ally,	ATel: 16608 (2nd May), 16610, 16611
Mp,	Glitch time: Between 20:52:11.4 and
dip,	~7 second uncertainty
allijo	$\Delta\Omega/\Omega \approx 2.4 \times 10^{-6}$
Mp,	Hanford, Livingston, Virgo all obse

	Naïve	Vortex unpinning
E _{GW} [erg]	1.2×10^{43}	1.4×10^{39}
$max(\rho)$	137.8	1.5

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High priority transient continuous gravitational wave targets

itched on 29th April 2024!

1, 16615, 16619 l 20:52:18.1

erving during glitch

5 Transient mountain 2.4×10^{42} 61.6 *f*-mode calculation (Yim & Jones 2023) gives: $\rho = 50, 25, 7,$ for Livingston, Hanford and Virgo (but using $\beta = 1$)

Part IV - Summary

Summary

- The SNR of a transient CW source can be estimated by obtaining E_{GW} .
- We explored 6 different models associated with pulsar glitches.
- For a sufficiently long transient CW, we can make a better estimate of the SNR by including information about the pulsar's sky position.
- In O4, we will start putting upper limits on some of these models. As shown, this can already be done with Vela's latest glitch!

superfluidity, elasticity / plastic flow, viscosity, magnetic diffusion, temperature gradients, etc...

High priority transient continuous gravitational wave targets

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Must start considering what physics can be learnt from a (non-)detection:

Continuous Waves School at KIAA, Beijing

- 7th 11th July
- Invited lecturers:
 - Prof. Maria Alessandra Papa (Albert Einstein Institute) All .
 - Prof. Ian Jones (University of Southampton) All p.
 - Dr. David Keitel (University of the Balearic Islands) dip.
 - Dr. Lilli Sun (Australian National University)
 - Plus 6 guest speakers all.
 - Speak with me if you are interested!
 - Email: g.yim@pku.edu.cn
- Website: https://garvinyim.wixsite.com/home/cw-school-at-kiaa
- Hungary, Austria, Belgium, Luxembourg, Malaysia, Brunei, Singapore.

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High priority transient continuous gravitational wave targets

Visa-free nationalities: France, Germany, Italy, the Netherlands, Spain, Switzerland, Ireland,

