Neural simulation-based inference of the neutron star equation of state directly from telescope spectra

Continuous gravitational waves and neutron stars

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Neutron stars



- Neutron stars weight $M \sim 1 2M_{\odot}$ and have radii $R \sim 11 13$ km
- High baryon densities in core beyond terrestrial experiments
 - \rightarrow Constrain unknown physics of dense matter based on neutron star observations

[Brandes, Kaiser and Weise, Phys. Rev. D 108 (2023)]

Description of neutron stars

► Internal structure described by Tolman-Oppenheimer-Volkoff (TOV) equations

$$\frac{\partial P(r)}{\partial r} = -\frac{G_N}{r^2} \left(\varepsilon(r) + P(r) \right) \left(m(r) + 4\pi r^3 P(r) \right) \left(1 - \frac{2G_N m(r)}{r} \right)^{-1}$$

$$\frac{\partial m(r)}{\partial r} = 4\pi r^2 \varepsilon(r)$$
[Tolman, Phys. Rev. 55 (1939)] [Oppenheimer and Volkoff, Phys. Rev. 55 (1939)]

- ► Solution for given equation of state (EoS) $P(\varepsilon)$ and central energy density $\varepsilon(r = 0) = \varepsilon_c$
 - \rightarrow Solution for different ε_c yields (*M*,*R*)-relation



Neural SBI of the neutron star EoS directly from telescope spectra | Len Brandes

Equation of state

- ► EoS depends on the internal phases: phase transitions, crossover, ...
- Introduce general parametrization $P(\varepsilon, \lambda)$ that can describe variety of scenarios
 - \rightarrow Here: spectral parametrization with two parameters (λ_1 , λ_2)
- Bayesian inference of λ based on neutron star data ${\mathscr D}$

 $p(\lambda | \mathcal{D}) \propto p(\mathcal{D} | \lambda) \, p(\lambda)$



[Koio, AAPPS Bull, 31 (2021)]

[Lindblom, Phys. Rev. D 82 (2010)]

Previous + BW

Thermal X-ray spectra

- Thermal X-ray spectra s of low-mass binaries in quiescence (qLMXBs)
 - → Depend on mass-radius (M, R) and nuisance parameters $v = (N_H, d, \log(T_{eff}))$
 - \rightarrow Information on v from other observations
- Likelihood p(s|\u03c6, v) analytically intractable, inference in two steps: [Riley, Raaijmakers and Watts, MNRAS 478 (2018)]
 - 1. Infer (*M*, *R*) from telescope spectrum *s* using xspec package [Arnaud, ASP Conf. Ser. 17 (1996)]
 - 2. Use posteriors p(M, R|s) as likelihoods to infer EoS

 $p(s|\lambda) \propto \int dM dR \ p(M,R|s)\delta(R-R(M,\lambda))$



Inference directly from telescope spectra

- Can sample from likelihood: for given λ_i sample (M_i, R_i) and (independently) ν_i
 - \rightarrow Simulate spectrum $s_i \sim p(s|\lambda_i, v_i)$ with xspec and add noise
 - → Here use NSATMOS model and Chandra response function [Heinke *et al.*, Astrophys. J. 644 (2006)]
- Train neural network to regress (λ₁, λ₂) from spectrum and nuisance parameters [Farrell *et al.*, JCAP 02 (2023)]

- Train neural network to predict spectra s for given (M, R, v)
 - \rightarrow Approximate likelihood p(s|M, R, v)
 - \rightarrow Compute $p(s|\lambda, v)$ with second neural network







Neural likelihood estimation

- Previous approaches only point estimates of EoS parameters or expensive likelihood evaluation
 - \rightarrow Marginalized over nuisance parameters
- Neural likelihood estimation: train neural density estimator to approximate likelihood

 $q_{\Phi}(\boldsymbol{s}|\boldsymbol{\lambda},\boldsymbol{v})\approx p(\boldsymbol{s}|\boldsymbol{\lambda},\boldsymbol{v})$

[Papamakarios, Sterratt and Murray, AISTAT (2019)]



Neural likelihood estimation

- Normalizing flows can model complicated probability distributions in high dimensions
 [Dinh, Sohl-Dickstein and Bengio, arXiv:1605.08803 (2016)]
 - → Represent probability distribution via invertible and differentiable transformations $f_{\Phi_1} \circ \cdots \circ f_{\Phi_N}$
- Minimizing statistical distance is equivalent to maximizing log probability

$$\min_{\Phi} D_{\mathsf{KL}} \left(p(\boldsymbol{s}|\boldsymbol{\lambda}, \boldsymbol{v}) \middle| \middle| q_{\Phi}(\boldsymbol{s}|\boldsymbol{\lambda}, \boldsymbol{v}) \right) = \max_{\Phi} \int d\boldsymbol{s} \ p(\boldsymbol{s}|\boldsymbol{\lambda}, \boldsymbol{v}) \left[\log p - \log q_{\Phi} \right]$$
$$= \max_{\Phi} \sum_{\boldsymbol{s}_{i} \sim p(\boldsymbol{s}|\boldsymbol{\lambda}_{i}, \boldsymbol{v}_{i})} \log q_{\Phi}(\boldsymbol{s}_{i}|\boldsymbol{\lambda}_{i}, \boldsymbol{v}_{i})$$

• Train 100 flows, use **ensemble average** over N = 5 best-performing

$$\log p(\boldsymbol{s}|\boldsymbol{\lambda},\boldsymbol{v}) \approx \frac{1}{N} \sum_{j} \log q_{\Phi_j}(\boldsymbol{s}|\boldsymbol{\lambda},\boldsymbol{v})$$



Neural likelihood estimation

- Multiply with priors and sample from posterior $p(\lambda, v|s) \propto p(s|\lambda, v)p(\lambda)p(v)$
 - → Uniform prior on EoS parameters $p(\lambda)$ $\lambda_1 \in [4.75, 5.25]$ $\lambda_2 \in [-2.05, -1.85]$
 - \rightarrow **Different scenarios** for prior information on nuisance parameters p(v)

parameter	true	tight	loose
d	exact	5%	20%
N _H	exact	30%	50%
$\log(T_{\rm eff})$	exact	±0.1	±0.2

Scaling to multiple observations

$$p(\lambda, v_{1...J}|s_{1...J}) \propto \left(\prod_{j} p(s_{j}|\lambda, v_{j})p(v_{j})\right) p(\lambda)$$

- High dimensional parameter space
 - \rightarrow Likelihood differentiable $\nabla_{\lambda,\nu} p(s|\lambda,\nu)$, can use **Hamiltonian Monte Carlo** (HMC) sampling

Example posterior distribution

- Full posterior p(λ, v|s) directly from telescope spectra
 - \rightarrow Here: based on 10 simulated spectra for example EoS
- ► Three scenarios: true, tight and loose
 - \rightarrow Uncertainties much smaller in true case
- ► Constrain *N_H* and log(*T*_{eff}) much better than prior information
 - \rightarrow In tight case *d* posterior similar to prior
- ► Transform into P(ε) and R(M) constraints using TOV equations



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[[]LB et al., arXiv:2403.00287 (2024)]

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Average performance on test set

- Compute maximum-a-posteriori estimate ($\lambda_{1,pred}, \lambda_{2,pred}$) for 100 random EoS
 - \rightarrow Again 10 simulated spectra for each EoS
- Compare to ground-truth values $(\lambda_{1,true}, \lambda_{2,true})$
 - \rightarrow Distribution centered around 0, **no systematic bias**



[LB et al., arXiv:2403.00287 (2024)]

Average performance on test set

Compare total standard deviation to previous approaches

$$\sigma_{\rm tot} = \sqrt{\sigma_{\lambda_1}^2 + \sigma_{\lambda_2}^2}$$

 \rightarrow Better accuracy than previous approaches

p (v)	method	$\sigma_{ m tot}$
true	NN(Spectra)	0.099
	ML-Likelihood	0.096
	NLE	0.090
tight	NN(Spectra)	0.115
	ML-Likelihood	0.112
	NLE	0.097
loose	NN(Spectra)	0.152
	ML-Likelihood	0.120
	NLE	0.113

[LB et al., arXiv:2403.00287 (2024)]

► For the first time posterior for nuisance parameters

Increasing number of observations

- Amortization: need to train normalizing flows only once
 - → Inexpensive likelihood evaluation, inclusion of additional observations straightforward
- ► Many more measurements in the future

[lacovelli et al., Phys. Rev. D 108 (2023)]

- \rightarrow Not feasible to use two-step method with integrations
- Extend neural likelihood estimation to other neutron star data [Dax et al., Phys. Rev. Lett. 127 (2021)]
- ► Apply to real data and include mass in likelihood q_Φ(λ, ν, M|s) [Steiner *et al.*, MNRAS 476 (2018)]



[[]LB et al., arXiv:2403.00287 (2024)]

Summary

- ► Bayesian inference of neutron star EoS based on thermal X-ray spectra
 - \rightarrow Likelihood analytically intractable \rightarrow Inference in two steps
- ► Neural likelihood estimation: train normalizing flows to approximate likelihood

 $q_{\phi}(s|\lambda, v) \approx p(s|\lambda, v)$

- \rightarrow Full posterior directly from telescope spectra
- \rightarrow Better accuracy than previous methods
- Inexpensive inclusion of additional data
 - \rightarrow More scalable to growing number of observations expected in coming years

Supplementary material

Comparison with two-step method

- Use xspec to predict mass and radius of neutron stars
 - \rightarrow Repeat for multiple v_i from p(v) to estimate ΔM and ΔR
- Train neural network to predict λ :



[Farrell et al., JCAP 02 (2023)]

► Compare accuracy:

$\mathcal{D}(\mathcal{V})$	method	$\sigma_{ m tot}$
true	NN(<i>M</i> , <i>R</i> via xspec)	0.085
	NLE	0.090
tight	NN(M, R via xspec)	0.098
	NLE	0.097
loose	NN(<i>M</i> , <i>R</i> via xspec)	0.136
	NLE	0.113

[LB et al., arXiv:2403.00287 (2024)]

Spectral EoS parametrization

Begin with relativistic mean-field model GM1L

 \rightarrow Describe by spectral expansion

$$\Upsilon(P) = \frac{1 - c_s^2}{c_s^2}$$
 with $c_s^2 = \frac{\partial P}{\partial \varepsilon}$

• Expand in effective enthalpy $h = \int_0^P dP' \ (\varepsilon(P') + P')^{-1}$

$$\Upsilon(h) = \exp\left[\sum_{k} \lambda_k \Phi_k(h)\right] \quad \text{with} \quad \Phi_k = \left[\log\left(\frac{h}{h_0}\right)\right]^k$$

 \rightarrow Second-order expansion already sufficient to describe EoS up to 10%

[Lindblom, Phys. Rev. D 82 (2010)]

• Vary parameters (λ_1, λ_2) for 10^3 EoS with ~ 100 stars (M, R) each

[Typel et al., Phys. Rev. C 81 (2010)]

[Lindblom, Phys. Rev. D 82 (2010)] [Lindblom, Phys. Rev. D 97 (2018)]

Hamiltonian Monte Carlo

Random-walk Metropolis

• Generate chain of samples of target distribution $\pi(q)$

 \rightarrow With gradients can reduce correlations and improve over random walks

Potential and kinetic term inspired by classical mechanics

$$H(p,q) = -\log \pi(q) + \frac{1}{2} p^{T} M^{-1} p$$
 [Betancourt, arXiv:1701.02434 (2017)]

- ► Sample auxiliary 'momentum' based on covariance $p \sim \mathcal{N}(0, M^{-1})$
 - \rightarrow Solve **Hamiltonian equations** with leap frog integrator for (q', p')
 - $\frac{dq}{dt} = \frac{\partial H}{\partial p} \qquad \frac{dp}{dt} = -\frac{\partial H}{\partial q}$
- ► Metropolis-Hasting: accept new state q' with probability

 $\min\left[1, \exp\left(-H(q', p') + H(q, p)\right)\right]$





Hamiltonian Monte Carlo

Normalizing flows

 Represent probability distribution p(x) via invertible and differentiable transformations f_Φ of base distribution π(u)

[Papamakarios et al., J. Mach. Learn. Res. 22 (2021)]

- Choose simple **base distribution** $\pi(u)$, i.e. standard Gaussian
- Generate samples

$$u \sim \pi(u)$$
 $x = f_{\Phi}(u)$

Compute probability density

$$p(x) = \pi(f_{\Phi}^{-1}(x)) \left| \det\left(\frac{\partial f_{\Phi}^{-1}}{\partial x}\right) \right|$$

- → Transformation should be easily invertible and have fast computable Jacobian determinant
- Stack multiple transformations $f_{\Phi} = f_{\Phi_1} \circ \cdots \circ f_{\Phi_N}$





Masked Autoregressive Flows

► Each dimension x of $(x_1,...,x_D)$ sequentially transformed based on previous $x_{1:d-1} = (x_1,...,x_{d-1})$

$$p(x) = \prod_{d=1}^{D} p(x_d | x_{1:d-1})$$
[Papamakarios, Pavlakou and Murray, NeurIPS 30 (2017)]

- Choose Gaussian marginals $p(x_d|x_{1:d-1}) = \mathcal{N}(x_d|\mu_d, \sigma_d^2)$
 - \rightarrow Mean and standard deviation computed by NN based on previous values
 - \rightarrow Sampling is equivalent to scaling and shifting standard Gaussian

 $x_d = \mu_d + \sigma_d u_d \qquad u_d \sim \mathcal{N}(0, 1)$

[Kingma et al., NeurIPS 29 (2016)]

- ► For inverse do not need to invert NN, autoregressive structure leads to triangular Jacobian
- Choose binary masks to compute all u_d in single pass

 \rightarrow Very efficiently obtain p(x), less efficient sampling x

Low-mass binaries in quiescence

- ► Low-mass donor star transferring material onto neutron star
 - \rightarrow Minimal X-ray radiation during **low-accretion periods**
- Luminosity given by distance and bolometric flux

 $L = 4\pi d^2 F$

- \rightarrow Flux partly absorbed by interstellar medium depending on N_H
- ► Assume uniform temperature → Stefan-Boltzmann law

 $L = \sigma_{\rm SB} 4\pi R^2 T_{\rm eff}^4$

- \rightarrow Needs to account for gravitational redshift and light-bending (depending on M/R)
- Radius from eight qLMXBs:

 $R(1.4 M_{\odot}) = 12.0^{+1.1}_{-0.6} \,\mathrm{km}$

[Heinke et al., Astrophys. J. 598 (2003)]

[Steiner et al., Mon. Not. Roy. Astron. Soc. 476 (2018)]

Multimodal masses

► Parameters close to border of prior (\(\lambda_1, \lambda_2\)) = (4.77, -1.91) in true scenario

3

 $[^{\odot}M]_{M}$

- \rightarrow Some chains **converge at wrong** $M^{(2)}$ and wrong λ
- Radius has larger impact on spectrum than mass
- Likelihood of false mode 10⁻⁴ times smaller

